

## COMMUNICATION

**A SIMPLE EXISTENCE CRITERION FOR  $(g < f)$ -FACTORS\***

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Received 6 March 1990

We simplify the criterion of Lovász for the existence of a  $(g, f)$ -factor when  $g < f$ , or when the graph is bipartite. Moreover, we give a simple direct proof, implying an  $O(\sqrt{g(V)} \cdot |E|)$  algorithm, for these cases. We then illustrate the convenience of the new criterion by deriving some old and some new facts about  $(g, f)$ -factors and  $[a, b]$ -factors.

Let  $G$  be a graph and let  $f$  and  $g$  be integer functions on the vertex set of  $G$  such that  $0 \leq g(x) \leq f(x) \leq \deg_G(x)$  for each vertex  $x$  of  $G$ . A  $(g, f)$ -factor of  $G$  is a spanning subgraph  $F$  of  $G$  with the property that  $g(x) \leq \deg_F(x) \leq f(x)$  for each vertex  $x$  of  $G$ . When  $g = a$  and  $f = b$  are constants, it is customary to write square brackets; that is, we have an  $[a, b]$ -factor. If  $f$  is any real function on a set  $S$ , we let  $f(S) = \sum_{x \in S} f(x)$ . Lovász characterized graphs which admit a  $(g, f)$ -factor. His criterion is the following (cf. [11, 12]):

**Theorem L.** *The graph  $G$  has a  $(g, f)$ -factor if and only if for every pair of disjoint sets  $S$  and  $T$ ,*

$$\varepsilon(S, T) + \tau(S, T) - \deg_G(T) \leq f(S) - g(T).$$

(Here  $\varepsilon(S, T)$  denotes the number of edges between  $S$  and  $T$ , and  $\tau(S, T)$  denotes the number of components  $C$  of  $G - (S \cup T)$  such that  $\varepsilon(T, V(C)) + f(V(C))$  is odd and  $f(x) = g(x)$  for all  $x \in V(C)$ . The expression  $\deg_G(T)$  is defined by our general convention as the sum of  $\deg_G(x)$  over the set  $T$ .)

\* We acknowledge NSERC support from grants A7829, A5075, and A3583.

Compare this criterion with the well known characterization of Tutte [14] of graphs with a 1-factor: The graph  $G$  has a  $[1,1]$ -factor if and only if for every set  $S$  the number of odd components of  $G - S$  is at most  $|S|$ . Tutte's criterion depends on only one set  $S$  rather than the pair of sets  $S, T$  of the above theorem. LasVergnas generalized Tutte's theorem to give a one-set criterion for the existence of  $(g, f)$ -factors in the special case when  $g \leq 1$ , [10]:

**Theorem LV.** Assume that  $g(x) \leq 1$  for each vertex  $x$  of  $G$ . Then  $G$  has a  $(g, f)$ -factor if and only if for every set  $S$ ,

$$g(I_S) + \sigma(S) \leq f(S).$$

(Here  $I_S$  is the set of isolated vertices of  $G - S$  and  $\sigma(S)$  denotes the number of other odd components  $C$  of  $G - S$  such that  $f(x) = g(x) = 1$  for all  $x \in V(C)$ .)

We give below a one-set criterion for the existence of  $(g, f)$ -factors for the special case when  $g < f$ . The same criterion also applies when the graph  $G$  is bipartite. It is not difficult to derive these results directly from Lovász' theorem as stated above, or from the simpler (but still two-set) formulations for the cases  $g < f$  or  $G$  bipartite in [12, 10.2.27–28]. However, the situation allows for a much simpler direct proof, from which one can also extract an efficient algorithm.

**Theorem 1.** Assume that one of the following two conditions holds:

(i) for every vertex  $x$  of  $G$  we have  $g(x) < f(x)$  or (ii) the graph  $G$  is bipartite. Then  $G$  has a  $(g, f)$ -factor if and only if for every set  $S$

$$\sum_{x \notin S} (g(x) \dot{-} \deg_{G-S}(x)) \leq f(S).$$

(Here ' $\dot{-}$ ' denotes the 'monus' function defined for real numbers  $a, b$  by  $a \dot{-} b = \max(0, a - b)$ .)

**Proof.** As mentioned above, this can be deduced from Lovász' theorem. However, the general proofs of Lovász' theorem [11, 12, 16, 6] are quite complex. We present a very simple alternating-path proof. First of all, if  $G$  has a  $(g, f)$ -factor  $F$ , then for any set  $S$  and any  $x \notin S$  for which  $\deg_{G-S}(x) < g(x)$ , there must be in  $F$  at least  $g(x) - \deg_{G-S}(x)$  edges from  $x$  to  $S$ . Thus  $\sum_{x \notin S} (g(x) \dot{-} \deg_{G-S}(x))$  is at most the number of edges from  $G - S$  to  $S$ , which is at most  $f(S)$ . Thus the necessity of the condition follows. To prove the sufficiency, assume that  $G$  has no  $(g, f)$ -factor, and let  $F$  be a  $(0, f)$ -factor which minimizes the quantity

$$\delta(F) = \sum_{x \in V(F)} (g(x) \dot{-} \deg_F(x)).$$

(Note that the empty graph is a  $(0, f)$ -factor of  $G$ ) Let  $U$  denote the set of vertices  $x \in V(G)$  for which  $\deg_F(x) < g(x)$ . By minimality of  $\delta(F)$  we can assume that

each edge joining two vertices of  $U$  belongs to  $F$ . We also assume that  $\delta(F) > 0$ . A  $u$ -alternating path with respect to  $F$  is a sequence of vertices of  $G$ ,  $u_1, u_2, \dots, u_k = u$  such that  $u_1 \in U$ , and, for each  $i$ ,  $u_{2i} u_{2i+1} \in E(F)$ ,  $u_{2i-1} u_{2i} \notin E(F)$ ; the path is even respectively odd if  $k$  is even respectively odd. Let  $S$ , respectively  $T$ , be the set of vertices  $u \notin U$  for which there exists an even, respectively odd,  $u$ -alternating path. It follows from the minimality of  $\delta(F)$ , that for  $x \in S$ ,  $\deg_F(x) = f(x)$  and for  $x \in T$ ,  $\deg_F(x) = g(x)$ . (If, say,  $k$  were even and  $\deg_F(u_k) < f(u_k)$  then the symmetric difference of  $F$  and the alternating path  $u_1, u_2, \dots, u_k$  would be a  $(0, f)$ -factor with smaller  $\delta$ .) It also follows from these definitions that if  $xy$  is an edge of  $F$ , then  $x \in S$  implies  $y \in T \cup U$ , and if  $xy$  is an edge of  $G$  but not of  $F$  then  $x \in T \cup U$  implies  $y \in S$ . Note that either of our assumptions, (i) or (ii), guarantees that  $S$  and  $T$  are disjoint. Thus, for  $x \in T \cup U$ ,

$$\deg_{G-S}(x) = \deg_F(x) - d_{F,S}(x) \leq g(x),$$

where  $d_{F,S}(x)$  is the number of edges of  $F$  joining  $x$  to  $S$ . Therefore,

$$\begin{aligned} \sum_{x \notin S} (g(x) - \deg_{G-S}(x)) &\geq \sum_{x \in T \cup U} (g(x) - \deg_{G-S}(x)) \\ &= \sum_{x \in U} (g(x) - \deg_F(x)) + \sum_{x \in T \cup U} d_{F,S}(x) > f(S), \end{aligned}$$

since  $\sum_{x \in T \cup U} d_{F,S}(x) = f(S)$  and  $U$  is non-empty.  $\square$

The same proof can also be seen to imply that the minimum  $\delta(F)$  of a  $(0, f)$ -factor  $F$  satisfies the following minmax relation (cf. [5]):

**Corollary 1.**  $\min_F \delta(F) = \max_S (\sum_{x \notin S} (g(x) - \deg_{G-S}(x)) - f(S)).$

Moreover, if we define an augmenting path in  $G$  with respect to a  $(0, f)$ -factor  $F$  to be either an even  $u$ -alternating path with  $\deg_F(u) < f(u)$ , or an odd  $u$ -alternating path with  $\deg_F(u) > g(u)$ , then the above proof shows that  $F$  minimizes  $\delta(F)$  if and only if it does not admit an augmenting path. Since each search for an augmenting path can be performed by breadth first search in time  $O(|E|)$  and the corresponding augmentation lowers the value  $g(x) - \deg_{G-S}(x)$  for at least one vertex  $x$ , we have a very simple  $(g, f)$ -factor algorithm of time complexity  $O(g(V) \cdot |E|)$ . Using a reduction to flows [6], or to matchings [4], we find  $O(\sqrt{f(V)} \cdot |E|)$  algorithms. In [7], we give  $O(\sqrt{g(V)} \cdot |E|)$  algorithms based on a direct generalization of [8]. (By a more complex route we also give  $O(\sqrt{g(V)} \cdot |E|)$  algorithms for the general  $(g, f)$ -factor problem, [7].)

We also have a common generalization to Theorems LV and 1; a one-set condition is given in [6] for the case where no vertex  $x$  has  $f(x) = g(x) \geq 2$ . (The condition differs from that given in Theorem 1 only in having the left-hand side increased by the quantity  $\sigma(S)$ .) Further generalizations and one-set criteria are given in [2].

**Corollary 2.** *Let  $g$  and  $f$  be as in Theorem 1. If for all pairs of vertices  $x, y$  of  $G$ ,*

$$g(y)/\deg_G(y) \leq f(x)/\deg_G(x),$$

*then  $G$  has a  $(g, f)$ -factor.*

**Proof.** The first observation to make is that for any set  $S$ ,

$$\sum_{x \notin S} (\deg_G(x) - \deg_{G-S}(x)) \leq \deg_G(S).$$

Then, letting  $W = \{x \notin S : g(x) \geq \deg_{G-S}(x)\}$ , we verify the condition of Theorem 1 as follows:

$$\begin{aligned} & f(S) - \sum_{x \notin S} (g(x) - \deg_{G-S}(x)) \\ & \geq (f(S)/\deg_G(S)) \sum_{x \notin S} (\deg_G(x) - \deg_{G-S}(x)) - \sum_{x \notin S} (g(x) - \deg_{G-S}(x)) \\ & = (1/\deg_G(S)) \left[ \sum_{x \in W} ((f(S)\deg_G(x) - \deg_G(S)g(x)) \right. \\ & \quad \left. + (\deg_G(S) - f(S))\deg_{G-S}(x)) \right. \\ & \quad \left. + f(S) \sum_{x \notin S \cup W} (\deg_G(x) - \deg_{G-S}(x)) \right] \geq 0. \quad \square \end{aligned}$$

We now turn to  $[a, b]$ -factors.

**Corollary 3.** *Let  $1 \leq a < b$  and let  $n(S, j)$  denote the number of vertices of  $G - S$  of degree  $j$ . Then  $G$  has an  $[a, b]$ -factor if and only if for any set  $S$*

$$\sum_{0 \leq j < a} (a - j)n(S, j) \leq b \cdot |S|.$$

Corollary 3 generalizes an earlier result of Berge and Las Vergnas [3] for  $[1, b]$ -factors,  $b \geq 2$ . (Since  $a = 1$ , the left-hand side reduces to  $|I_S|$ .) Theorem 1 also implies further extensions. For instance, if  $1 \leq a < b$ , and if  $T$  is a given set of vertices of  $G$ , then  $G$  has a  $[0, b]$ -factor  $F$  with  $a \leq \deg_F(x) \leq b$  for all  $x$  in  $T$ , if and only if  $\sum_{0 \leq j < a} (a - j)n(S, T, j) \leq b \cdot |S|$ , where  $n(S, T, j)$  denotes the set of vertices of  $T$  having degree  $j$  in  $G - S$ . Corollary 2 generalizes the following result of Kano and Saito [9]: if  $a < b \leq n$  and  $a/b \leq m/n$ , then every  $[m, n]$ -graph has an  $[a, b]$ -factor. (An  $[m, n]$ -graph has all degrees between  $m$  and  $n$ .) This was first proved by Tutte [15] for  $n = m$  and  $b = a + 1$ , and by Thomassen [13] for  $n = m + 1$  and  $b = a + 1$ . By repeated application of these results we obtain the following:

**Corollary 4.** *An  $[m, n]$ -graph has  $k$  edge-disjoint  $[a, b]$ -factors if*

$$mb - na \geq (k - 1)(b^2 - a^2) \quad \text{and} \quad a < b \leq n - (k - 1)a.$$

So, in particular, under the conditions  $r \geq (k - 1)(a + b)$  and  $a < b \leq r - (k - 1)a$  every  $r$ -regular graph has  $k$  disjoint  $[a, b]$ -factors.

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